

NEW ASTRO-GEODETIC MEASUREMENTS FOR GEOID MODELING

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Abstract. The paper presents the results obtained in four points regarding the astro-geodetic vertical deviation determination. The four points located in the metropolitan area of Bucharest city and they are stationed twice, in 2015 and 2023. Observations were realized by a platform composed by an electronic total station coupling with a micro-CCD camera and a GPS time receiver, all controlled by a portable PC. For every station were realized more sessions of observations in both years. For vertical deviation calculus we used geodetic coordinates extracted from models, while astronomical coordinates were measured in the field. The goal of these astro-geodetic determinations is to serve for testing and evaluating global geoid models as EGM2008 and GOCE, as well as to validate the historical astro-geodetic determinations in our country.

Key words: astrometry, geodesy, CCD, vertical deviation.

1. INTRODUCTION

Astro-geodetic observations represent the combination of two different approaches regarding positioning on the Earth surface. Astronomical observations basically mean ground astrometry with adequate instruments for as precise and accurate as possible determination of the observation point position on the Earth's topographical surface. The result of astronomical the observations is the latitude Φ and longitude Λ , called astronomical coordinates, in accordance with the name of the determination method. The second approach for positioning is by geodetic techniques which provide, for the same point on the Earth's surface the second coordinates set called geodetic latitude ϕ and longitude λ . The geodetic positioning implies either

geodetic terrestrial measurements or satellite/GNSS (Global Navigation Satellite System) determinations. So, in the same point on the Earth's surface we have two different coordinates pairs: (Φ, Λ) and (ϕ, λ) .

In present, several long-wave global geoid models (smooth surfaces) are developed and mainly serve as reference for a better global or zonal geoid model. The combination between the global models augmented by local and regional data from terrestrial measurements is a suitable solution for obtaining a high-resolution geoid. Terrestrial methods as the astro-geodetic one are able to detect short wavelength structures of the geoid beside gravimetric, GNSS (Global Navigation Satellite System) and levelling methods. All these terrestrial methods have both advantages and disadvantages, general rule being their common use. Despite the well-known difficulties in obtaining, one of the most valuable quantities used for geoid determination or geoid modelling is the Helmert astro-geodetic vertical deviation (v.d.). Helmert v.d. is considered “... *rich in high-frequency gravitational information, observed values of the astronomic (or Helmert) deflections are well suited to assess the high-degree spectrum of a geopotential model*” (Jekeli, 1999), and for this reason is used in several exhaustive studies concerning validation of the global geoid models as GOCE (Gravity field and steady-state Ocean Circulation Explorer) or EGM2008 (Earth Gravitational Model 2008). At the international level, there are some ongoing projects, the geoid problem, both at global level or regional level being an actual problem of geodesy (Featherstone W.E. and Morgan L., 2007; Hirt C., et al., 2010b; Voigt C. and Denker H., 2011).

2. INSTRUMENTS

As already described in our previous paper (Bădescu, O., et al, 2015, 2016a, 2010) the measuring platform is composed by a geodetic total station for precise angular measurement (Topcon MS05AX, 168 mm telescope length, 45 mm telescope aperture, $30\times$ telescope magnification, $0''.1$ minimum angular value displayed, $0''.5$ angular accuracy, with tilt angle compensator and 5 brightness levels for reticle illumination) to which was attached a small CCD camera (XIMEA MU9PM-MH, resolution 5MP, 2592×1944 pixels, sensor size 5.70×4.28 mm, pixel 2.2×2.2 μm , 20 μs –500 s) for automate determination of the intersection time of the star trajectory with the reticular wires of the total station telescope. A small GPS receiver ensures the time base for the time measurements and astrometric computations. The entire platform, including the observational process and the data adjustment is controlled by a laptop, thus the components ξ (meridian) and η (prime vertical) of the deviation of the vertical are obtained right after the observations are completed.

A time-based GPS receiver was built on a dedicated, modular Raspberry PI V3

Model B micro-computer and a Neo 6M v2 GPS receiver, with NMEA and PPS capabilities, connected to the motherboard of the micro-computer. The control and command of this time and position receiver is done via a web interface that permanently provides device status as well as synchronization and positioning details (Figure 1).

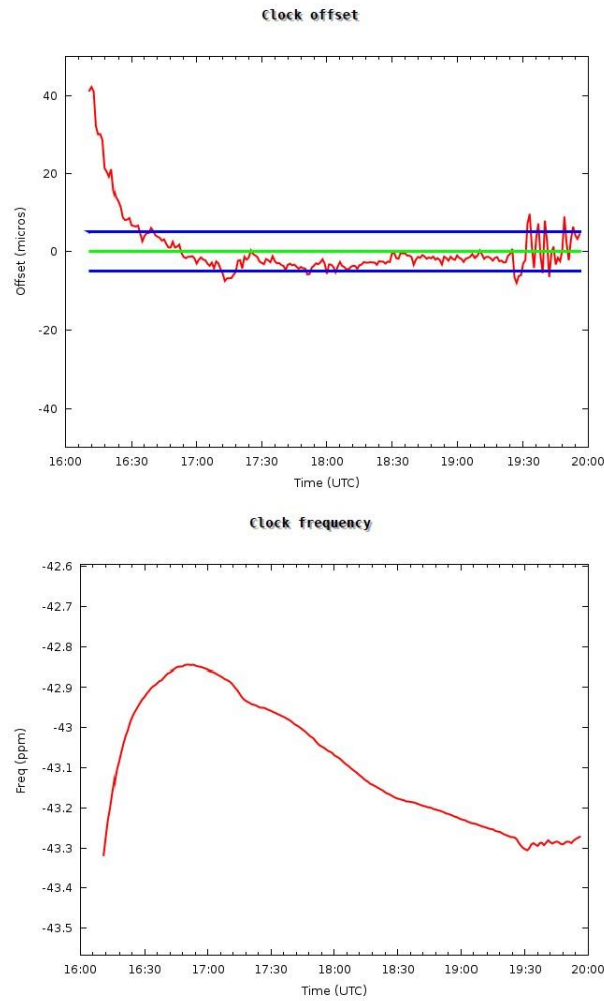


Fig. 1 – Clock offset and frequency during the observation session at 27.06.2023. *In situ* these parameters are observed permanently. In the case of some abnormal offset (over ± 5 microseconds) measurements are eventually interrupted.

The dedicated software for astro-geodetic measurements has a several characteristics, for using with a geodetic total station gifted by a CCD camera and the GPS time receiver, all being coupled on a portable PC. All components are connected to and controlled by the portable PC (Bădescu, O., et al, 2015, 2016a, 2010):

- Runs under Linux – Ubuntu operating system;
- Generate virtual reticular wires which can be translated on any direction and rotate (in step of 0.1 pixel for translations and 0.1 degree for rotation, or so-called auto-wire function);
- Ensures the time measurement by synchronizing with the external GPS time receiver via LAN port;
- It has functions for obtaining quality images – astrometric images, as: setting the time interval between consecutive images, gain, exposure time, image scale and detection sigma, create a master dark;
- Allow introduction of the star name, angular measurements from the geodetic instrument (azimuth and zenithal distance) as well as the atmospheric parameters (pressure, temperature and humidity), measured at the beginning or at the end of observations;
- No image is stored in the computer (acquisitions data laptop);
- At the end of the observations for every star separately provide the time of intersection with the virtual reticular wires (previously overlapped on the real reticular wires). Also, it is providing the image of the calculated trajectory and rms (root mean square) of the fitting (fitrms);
- Create a file which contain for each observed star, angular values and corresponding times, atmospheric parameters, images number and the fitrms of the trajectory fitting using star centroids separately for azimuthal and zenithal measurements;
- At the software application has been used ESO CPL (European Southern Observatory Common Pipeline Library), GTK (Graphic Toolkit) for interface and XIMEA SDK (Software Development Kit).

3. DATA AQUISITION

Astro-geodetic observations were made in four different locations from Bucharest city area and it's surroundings (Figure 2). Two locations are inside of the Bucharest city (AIRA – Astronomical Institute of the Romanian Academy and HTL – Hydro Technical Laboratory of the Bucharest Technical University of Civil Engineering), gifted by pilaster with forced centering and for other two, situated on the Bucharest ring road, observations were performed on the tripod of the total station (E – East and SE – South East). In addition, both locations inside Bucharest city area

show obstructions in certain directions, such as buildings or tall trees, thus unable to ensure a quite uniform azimuthal distribution of the observed stars. Lines of sight which pass over the buildings are affected by parasitic refractions caused by the warmer air around them. However, all the stations are relative improperly for astronomical (astrometric) observations, being affected by atmospheric and light pollution, characteristics of urban areas, or relative instability caused by using the tripod (Figure 3).

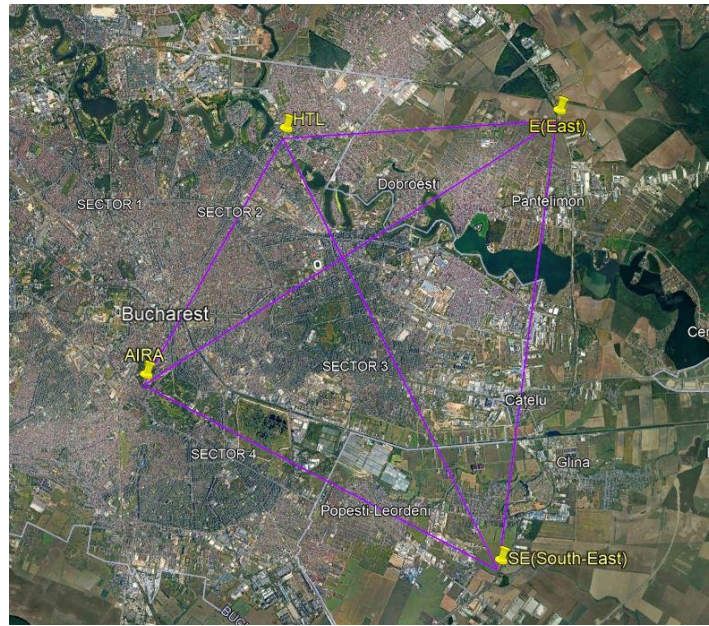


Fig. 2 – Four astro-geodetic points on the Bucharest area: AIRA, HTL, E and SE.

Approximative distance from points are: AIRA-HTL ~ 7.2 km, HTL-E ~ 7.1 km, E-SE ~ 11.7 km, SE-AIRA ~ 10.36 km and diagonals HTL-SE ~ 12.4 km and AIRA-E ~ 12.7 km.

All observations were made in both positions of the total station's telescope (Face 1 – Face 2) to limit residual instrumental errors and for every star the atmospheric parameters (pressure, temperature and humidity) were taken at the middle of the timing of observations. Every star was observed both azimuthal and zenithal. In some nights, the sequence Face 1 – Face 2 was replaced by Face 1 – Face 2 / Face 2 – Face 1 or Face 1 – Face 2 / Face 2 – Face 1 / Face 1 – Face 2 meaning a doubling or tripling the number of measurements for each observed star.

Every observed star generates 2 equations, one corresponding to the azimuthal observations and the second corresponding to the zenithal observations. So, for n observed stars, at least in the sequence Face 1 – Face 2, we will have $n \times 2$ equations.

For every observation night we aimed at achieving a uniform azimuthal distribution of the observed stars. These measurements were processed by a functional stochastic model based on the theory of conditional measurements with unknowns. Least square adjustment was used to find the unknowns of the models, that is astronomical latitude, longitude and azimuth of the station point (the last one is an additional result, unused for vertical deviation determination). Based on the measurement corrections (angular and time measurement) obtained after the least square adjustment, two statistical tests were used to eliminate the measurements considered erroneous.



Fig. 3 – Three stationed astro-geodetic points: left figure, HTL (pilaster, forced centering); center figure, AIRA (pilaster, forced centering) and right figure, the E station (stationed on the tripod of the total station).

According to the star apparent motion in the optical field (trajectory relative to the crosshairs and apparent speed), the number of the images captured for every observed star has varied from a few dozen to a few hundred. For every observed star, the exposure time varied according to the atmospheric conditions and the stars' magnitude (brightness), and the time interval between two consecutive images varied according to the apparent motion in the optical field. In general, for all of the observed stars it was intended that the trajectory passes as close as possible to the intersection of the crosshairs, symmetrical to this point and as short as possible (Figure 4, Figure 5).

Besides the angular values taken from the total station, the atmospheric parameters (pressure in mbar, temperature in °C and relative humidity in %) are introduced manually. All these parameters are written into a file data (Table 1). In Figure 5, left image, follow by right image, come from a Face 2 – Face 1 sequence, from $21^{\text{h}}22^{\text{m}}42^{\text{s}}.309$ to $21^{\text{h}}25^{\text{m}}30^{\text{s}}.457$, which means approximative 3 minutes. The

entire period of Face 2 – Face 1 sequences hold maximum 5-6 minutes.

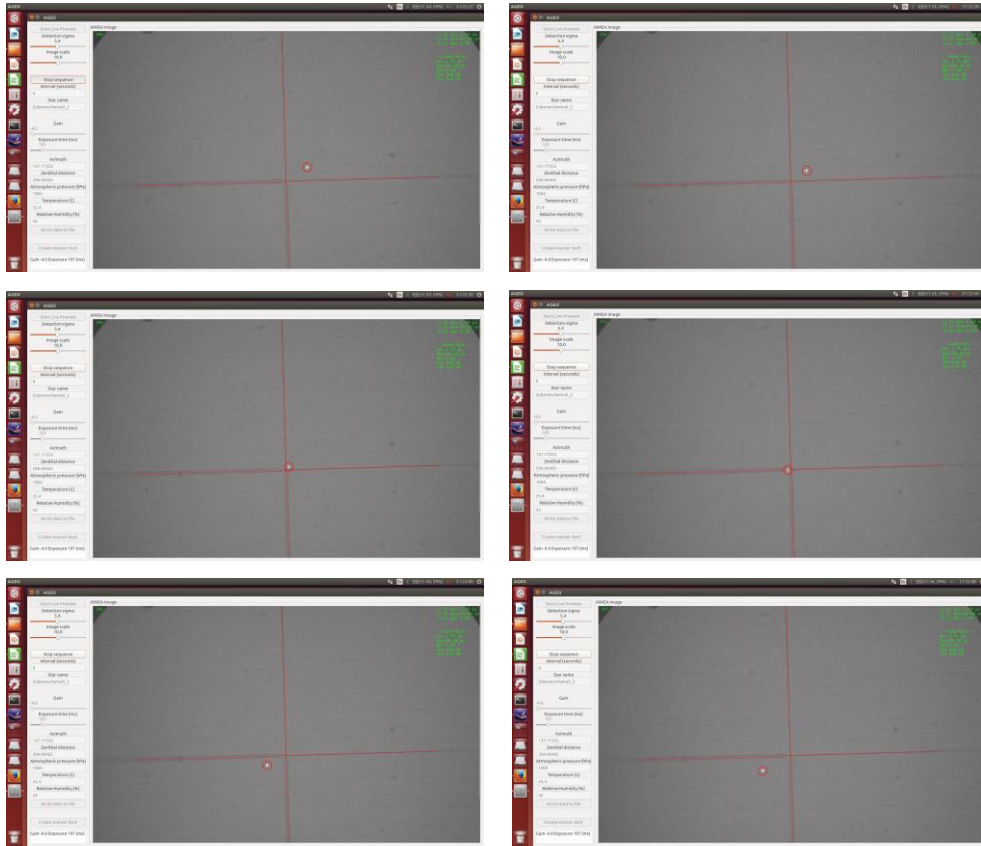


Fig. 4 – Six consecutive images random taken from almost 500 ones, for the star Zubeneshamali (Beta Librae, Absolute magnitude -1.16), in 21.06.2023, at AIRA station. The star trajectory is passing the reticular wires on diagonal and almost in the center (from the upper right corner to the lower left corner). The exposure time, as we can see in the images, was 197 ms and the interval from two consecutives images was 20 μ s.

In this conditions, 10 stars could be observed under one hour. Both images from Figure 5 comes from 21.06.2023, for the star Zubeneshamali, Face 2 – Face 1.

Angular values of the azimuth and the zenithal distance, calculating times corresponding to the angular values (moments corresponding to the intersection of the star trajectory with the crosshairs) and the atmospheric parameters are saved in an observations file (Table 1).

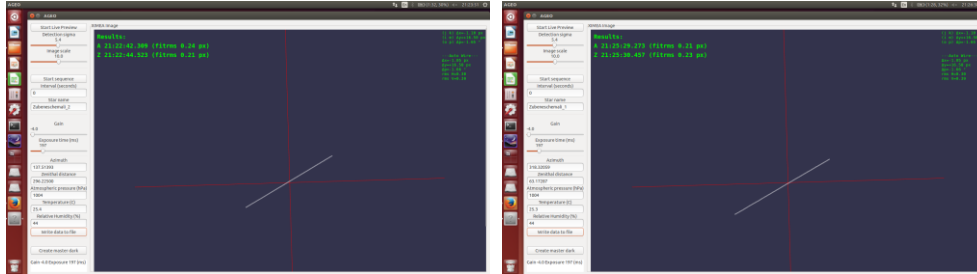


Fig. 5 – Times of crossing reticular wires, separately for vertical (A, azimuthal) and horizontal (Z, zenithal) wire and corresponding fits (in pixel) are automatically calculated by software. Angular values for azimuth and zenithal distance are taken from the total station. Both images come from a sequence Face 2 – Face 1 (Zubeneschamali 2 – Zubeneschamali 1), at AIRA station in 21.06.2023.

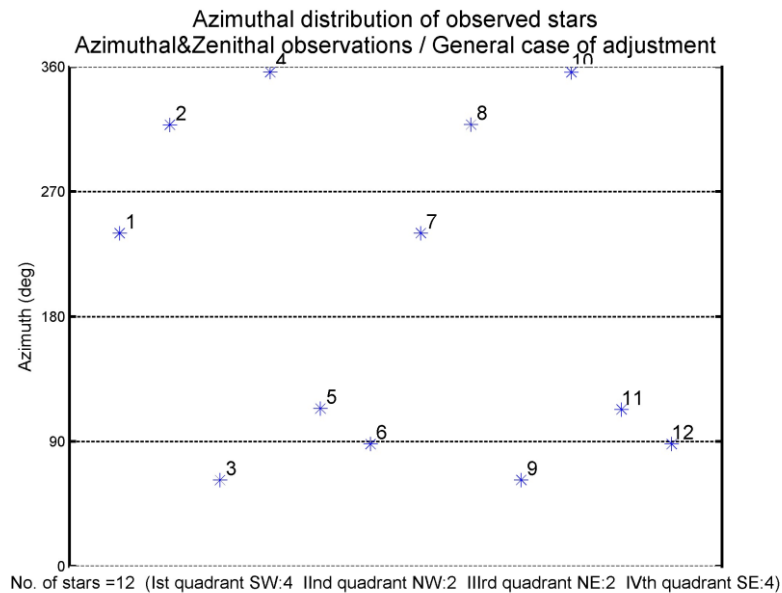


Fig. 6 – Azimuthal distribution of 12 observed stars in 21.06.2023. Each star marked on the above graphic come from a pair Face 1 – Face 2 or Face 2 – Face 1. Stars 2 and 8 is Zubeneschamali (twice observed Face 2 – Face 2 – Face 1 – Face 1), 1 and 7 is Vega, 3 and 9 Regulus and so on (see the Table 1).

Immediately after the observations are ended, the software application accesses the observations file and calculate the component of the vertical deviation and the total vertical deviation (ξ , η and ε), as well as a graphic with the azimuthal distribution of the observed stars into a single session (Figure 6).

Table 1

Lines of data from an observations file (stars observed in the Face 1 – Face 1 – Face 2 – Face 2 sequences at the station AIRA at 21.06.2023)

21.06.2023													
Passing clouds, visibility difficulties, different exposure times, reticular fires alignment verified, normal function of the GPS time receiver. From time to time, wind blowing. At the end of the night observation, the sky was totally covered by clouds, so the azimuthal uniform distribution was affected (for instance, Errai, the final observed star, it could no longer be observed in the Face 2 position). Some stars were observed through clouds.													
002	Vega_1	239.36459 ⁽¹⁾	64.33122 ⁽²⁾	1004.0 ⁽³⁾	25.6 ⁽⁴⁾	43.0 ⁽⁵⁾	21.0839059 ⁽⁶⁾	0.21 ⁽⁷⁾	416 ⁽⁸⁾	21.0838939 ⁽⁹⁾	0.27 ⁽¹⁰⁾	416 ⁽¹¹⁾	
003	Vega_1	239.57131	64.09571	1004.0	25.6	43.0	21.1113969	0.16	413	21.1109290	0.21	413	
004	Vega_2	60.17179	296.14505	1004.0	25.5	43.0	21.1346210	0.15	404	21.1348835	0.19	404	
005	Vega_2	60.34478	296.34393	1004.0	25.5	43.0	21.1559067	0.19	419	21.1556131	0.22	419	
006	Zubeneschemali_2	137.17353	296.06465	1004.0	25.4	43.0	21.2020666	0.23	517	21.2031337	0.22	517	
007	Zubeneschemali_2	137.51393	296.22500	1004.0	25.4	44.0	21.2242309	0.24	401	21.2244522	0.21	401	
008	Zubeneschemali_1	318.32059	63.17287	1004.0	25.3	44.0	21.2529272	0.21	435	21.2530456	0.23	435	
009	Zubeneschemali_1	318.58331	63.03153	1005.0	25.3	44.0	21.2717902	0.22	511	21.2731038	0.22	511	
010	Zubeneschemali_1	319.21373	62.53102	1005.0	25.3	44.0	21.2852357	0.24	456	21.2857186	0.22	456	
011	Regulus_1	61.10101	48.29192	1005.0	25.2	44.0	21.3237163	0.21	457	21.3239073	0.23	457	
012	Regulus_1	61.42035	48.48577	1005.0	25.1	44.0	21.3444424	0.20	403	21.3443833	0.21	403	
013	Regulus_2	242.23271	310.45100	1005.0	25.0	45.0	21.3731284	0.21	404	21.3727942	0.21	404	
014	Regulus_2	242.54280	310.24545	1005.0	25.0	45.0	21.3937547	0.22	405	21.3935279	0.23	405	
015	Spica_2	175.14552	304.13519	1005.0	24.7	45.0	21.4500137	0.23	408	21.4446646	0.27	408	
016	Spica_2	175.50020	304.15279	1005.0	24.7	45.0	21.4658383	0.20	408	21.4639277	0.20	408	
017	Spica_1	356.34024	55.42357	1005.0	24.5	46.0	21.4926299	0.21	407	21.4927852	0.21	407	
018	Spica_1	357.06133	55.41360	1005.0	24.6	46.0	21.5114569	0.22	409	21.5106887	0.22	409	
019	Castor_1	112.15214	66.26240	1005.0	24.3	46.0	21.5907253	0.24	455	21.5913372	0.24	455	
020	Castor_1	113.00231	67.18226	1005.0	24.1	47.0	22.0415651	0.26	405	22.0428259	0.28	405	
021	Castor_1	113.21038	67.38197	1005.0	24.1	47.0	22.0637139	0.26	454	22.0629748	0.32	454	
022	Castor_2	293.45033	291.56031	1005.0	24.0	47.0	22.0921027	0.28	508	22.0906352	0.30	508	
023	Castor_2	293.57053	291.39537	1005.0	23.8	48.0	22.1043181	0.28	456	22.1045354	0.37	456	
024	Castor_2	294.15020	291.18537	1005.0	23.9	47.0	22.1245731	0.26	425	22.1254011	0.35	425	
025	EpsLeo_2	267.18307	307.46152	1005.0	23.7	48.0	22.2006863	0.26	404	22.1958700	0.30	404	
026	EpsLeo_2	267.41027	307.23247	1005.0	23.7	48.0	22.2211006	0.30	416	22.2206398	0.32	416	
027	EpsLeo_1	88.04094	52.59000	1005.0	23.6	48.0	22.2418790	0.35	478	22.2411506	0.44	478	
028	EpsLeo_1	88.19414	53.14524	1005.0	23.6	48.0	22.2545230	0.28	432	22.2540320	0.32	432	
029	EpsLeo_1	88.42140	53.39148	1005.0	23.5	48.0	22.2751233	0.25	422	22.2756575	0.28	422	
030	Errai_1	188.22360	56.00122	1005.0	23.4	47.0	22.3331125	0.53	311	22.3303369	0.40	311	
031	Errai_1	188.32401	55.54572	1005.0	23.4	47.0	22.3631066	0.25	628	22.3623798	0.30	628	
032	Errai_1	188.37520	55.52424	1005.0	23.3	47.0	22.3804501	0.27	456	22.3747578	0.29	456	

Explanation for Table 1 (Călin, A., et al, 2018): ⁽¹⁾ Azimuthal angular value of the observed star, taken from the total station. ⁽²⁾ Zenithal angular value (zenithal distance)

of the observed star, taken from the total station. ⁽³⁾ Atmospheric pressure. ⁽⁴⁾ Atmospheric temperature. ⁽⁵⁾ Atmospheric humidity. ⁽⁶⁾ Time corresponding to the azimuthal angular value of the observed star (the moment of the star's crossing to the vertical reticular wire) in the Coordinated Universal Time scale (UTC). ⁽⁷⁾ The root mean square of a two-degree polynomial trajectory fitted on the star centroids from every captured image, for calculating the intersection time with the vertical reticular wire (azimuthal observation). Represent a measure of the quality for azimuthal observations. ⁽⁸⁾ The number of images used to calculate the trajectory and the intersection moment with the vertical reticular wire (azimuthal measurements). ⁽⁹⁾ Time corresponding to the zenithal angular value of the observed star (the moment of the star's crossing to the horizontal reticular wire) in the Coordinated Universal Time scale (UTC). ⁽¹⁰⁾ The root mean square of a two-degree polynomial trajectory fitted on the star centroids for the intersection with the horizontal reticular wire (zenithal observation). Represent a measure of the quality for zenithal observations. ⁽¹¹⁾ The number of images used to calculate the trajectory and the intersection moment with the horizontal reticular wire (zenithal measurements).

4. RESULTS

As already mentioned, currently, CCD technology become a key element in the astro-geodetic determinations. In the last decade, significant results were obtained by developing new instruments for astro-geodetic determinations, mostly based on zenithal cameras (former photographic zenithal tubes). These instruments have more features, among which we can mention it: do not need horizontal orientation, astronomical refraction has little influence near the zenith and are transportable (Bürki B., et al., 2007; Hirt, C., et al, 2002, 2004, 2010a).

All four points were stationed twice. First, during 2015 inside of the incipient test when the equipment's of astro-geodetic platform was purchased and assembled and second, in 2023, after some improvements regarding software, observations technique, the clamping system of the micro-CCD camera and other.

Results obtained for the four mentioned points are presented in the Table 2. For every point was realized more sessions, in the same night, with a variable number of observed stars, both for the 2015 and 2023. For instance, the point HTL was observed in 15.07.2015, three times, using 18, 8 and 12 stars for each session. The same point was observed in 13.07.2023, twice, using 18 and 8 stars for each session. For all session, stars were observed at least in the sequences Face 1 – Face 2, or even more.

Deviation of the vertical using for control and comparisons, meridian and prime vertical components too, come from Romanian historical astronomical observations realized by Topographical Military Directorate (DTM), GOCE spherical harmonic

Table 2

Values of deviations of the vertical resulting from CCD observations in the points HTL, E, SE and AIRA, during 2015 and 2023 comparative with values derived by interpolation from historical data (DTM), EGM2008 and GOCE global geoid models. $s_{(0)}$ standard deviation of a single series; $s_{(\xi)}$ standard deviation of the meridian component ξ , $s_{(\eta)}$ standard deviation of the prime vertical component η , all values expressed in arcseconds.

Station/Data	No. of observed stars	$s_{(0)}$ "	$s_{(\xi)}$ "	$s_{(\eta)}$ "	ξ "	η "	ξ " DTM	η " DTM	ξ " EGM2008	η " EGM2008	ξ " GOCE	η " GOCE
HTL/15.07.2015	18	1.313	0.571	0.714	11.065	3.226	11.619	4.060	11.221	3.935	9.457	4.711
	9	1.190	0.738	0.911	11.268	3.261	0.554	0.834	0.156	0.709	-1.608	1.485
	12	1.425	0.757	0.939	11.412	3.349	0.351	0.799	-0.047	0.674	-1.811	1.450
HTL/13.07.2023	18	0.889	0.357	0.496	11.872	3.280	0.207	0.711	-0.191	0.586	-1.955	1.362
	8	0.815	0.486	0.692	11.909	3.244	-0.253	0.780	-0.651	0.655	-2.415	1.431
Max					11.909	3.349	-0.290	0.816	-0.688	0.691	-2.452	1.467
Min					11.065	3.226						
Max-Min					0.844	0.123						
Average					11.505	3.272	Differences from the interpolated values and average					
Standard Deviation					0.373	0.047	-0.114	-0.788	0.284	-0.663	2.048	-1.439
E/27-07-2015	19	2.692	1.079	1.479	10.208	2.486	11.301	3.725	10.947	3.384	9.637	4.277
	12	1.437	0.708	0.974	10.813	2.543	1.093	1.239	0.739	0.898	-0.751	1.791
	10	2.971	1.586	2.353	10.732	2.603	0.488	1.182	0.134	0.841	-1.356	1.734
	14	2.961	1.452	1.876	10.924	2.817	0.569	1.122	0.215	0.781	-1.275	1.674
E/24-07-2023	14	1.737	0.799	1.106	10.325	2.444	0.377	0.908	0.023	0.567	-1.467	1.460
	7	1.869	1.216	1.731	10.795	2.021	0.976	1.281	0.622	0.940	-0.868	1.833
	12	1.575	0.766	1.106	10.745	2.532	0.506	1.704	0.152	1.363	-1.338	2.256
Max					10.924	2.817	0.556	1.193	0.202	0.852	-1.288	1.745
Min					10.208	2.021						
Max-Min					0.716	0.796						
Average					10.649	2.492	Differences from the interpolated values and average					
Standard Deviation					0.271	0.240	-0.652	-1.233	-0.298	-0.892	1.012	-1.785
SE/30-07-2015	12	1.910	1.007	1.258	9.864	4.192	10.769	4.038	10.646	3.957	9.978	4.127
	9	1.768	1.030	1.370	10.138	3.513	0.905	-0.154	0.782	-0.235	0.114	-0.065
SE/28-07-2023	16	1.392	0.640	0.816	10.956	3.281	0.631	0.525	0.508	0.444	-0.160	0.614
	8	1.441	0.938	1.195	11.033	3.327	-0.187	0.757	-0.310	0.676	-0.978	0.846
	8	1.496	0.973	1.241	10.880	3.235	-0.264	0.711	-0.387	0.630	-1.055	0.800
Max					11.033	4.192	-0.111	0.803	-0.234	0.722	-0.902	0.892
Min					9.864	3.235						
Max-Min					1.169	0.957						
Average					10.574	3.510	Differences from the interpolated values and average					
Standard Deviation					0.535	0.396	-0.195	-0.529	-0.072	-0.448	0.596	-0.618
AIRA/11-07-2015	19	0.944	0.385	0.505	12.819	3.381	11.759	4.364	11.015	4.379	9.644	4.742
	9	0.993	0.596	0.778	12.657	3.312	-1.060	0.983	-1.804	0.998	-3.175	1.361
	18	0.946	0.403	0.516	12.960	3.335	-0.898	1.052	-1.642	1.067	-3.013	1.430
	7	0.778	0.482	0.715	12.227	4.017	-1.201	1.029	-1.945	1.044	-3.316	1.407
AIRA/12.07.2015	18	1.067	0.434	0.612	12.257	3.684	-0.468	0.347	-1.212	0.362	-2.583	0.725
	11	1.219	0.622	0.907	12.390	3.834	-0.498	0.680	-1.242	0.695	-2.613	1.058
AIRA/20.06.2023	16	1.169	0.511	0.712	12.119	3.811	-0.631	0.530	-1.375	0.545	-2.746	0.908
AIRA/21.06.2023	16	1.053	0.429	0.682	12.073	3.174	-0.360	0.553	-1.104	0.568	-2.475	0.931
	8	1.036	0.598	0.950	12.068	3.343	-0.314	1.190	-1.058	1.205	-2.429	1.568
AIRA/27.06.2023	19	0.707	0.294	0.389	12.722	3.158	-0.309	1.021	-1.053	1.036	-2.424	1.399
Max					12.960	4.017	-0.963	1.206	-1.707	1.221	-3.078	1.584
Min					12.068	3.158						
Max-Min					0.892	0.859						
Average					12.429	3.505	Differences from the interpolated values and average					
Standard Deviation					0.333	0.304	0.670	-0.859	1.414	-0.874	2.785	-1.237

potential (using GUT) and EGM2008 global model, after a methodology described in detail in (Bădescu, O., et al, 2016b), by interpolation.

For the astronomical vertical deviation, geodetic coordinates are referred to ellipsoid GRS80 – ETRS89 (Geodetic Reference System 1980 – European Terrestrial Reference System 1989).

Related to the astrometric reductions, we mention that:

- The star catalogue used in the astrometric reductions was FK6 (Sixth Catalogue of Fundamental Stars);
- Astrometric reductions from J2000.0 catalogue epoch to observations epoch were done using a software based on NOVAS package of subroutines and functions (Naval Observatory Vector Astrometry Software, Version 3.1 Fortran, C, and Python Editions, <http://aa.usno.navy.mil/software/novas/>);
- Astrometric reductions were verified with MICA v.2.2.2 software application (Multiyear Interactive Computer Almanac, <http://aa.usno.navy.mil/software/mica/>);

Values of vertical deviation components incorporate the correction of the polar motion.

5. REMARKS AND CONCLUSIONS

In total, we achieved 11 observations' nights, in 4 different stations and 2 different years, 2015 and 2023, that means an interval of 8 years. In 3 stations were made 2 nights of observations, both in 2015 and in 2023. In 1 station (AIRA) were effectuated 2 nights of observations in 2015 and 3 in 2023. On the whole, in all 4 stations, were obtained 27 determinations of vertical deviations from which 15 in 2015 and 12 in 2023. 5 determinations were made at HTL station (from which 2 in 2023), 7 at E station (from which 3 in 2023), 5 at SE station (from which 3 in 2023), and 10 at station AIRA (from which 4 in 2023). The total number of the used stars in determinations, separately 2015 and 2023, is depicted in Figure 7.

For all station and for all observations sessions, were recorded the parameters fitrms, separately in azimuth and zenithal distance. The software calculates the centroid of the brightest object from every image using a bi-dimensional circular Gaussian function. Precision of the centroid detection is about of 1/20 pixel in the case of stars with detection sigma bigger than 5. Based on centroids, then is calculated, separately or simultaneous, times of intersections with the two axes (virtual reticular wires) using a function of order II for fitting. Also, it is providing the image of the calculated trajectory (Figure 5) and root mean square (rms) of the fitting – fitrms (see Explanation at Table 1, ⁽⁷⁾, ⁽¹⁰⁾). Figure 8 shows the average of the fitrms obtained in station AIRA, in 2023, separately for azimuth (A) and zenithal distance (Z). Figure 9

shows the average number of images captured for every observation night (the total number of captured images into a single night divided by the total number of the observed stars) and the total number of imaged captured into a single night, in station AIRA, in 2023.

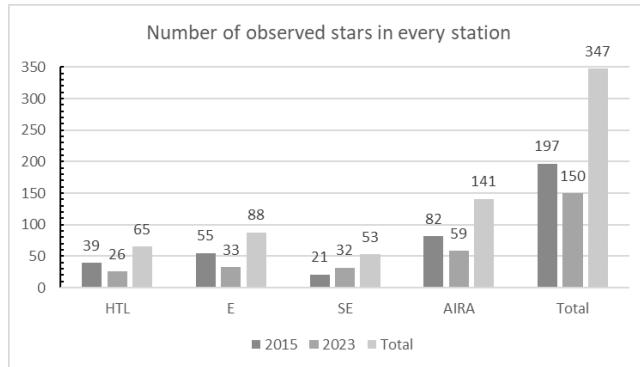


Fig. 7 – Number of observed stars in every station (HTL, E, SE and AIRA) as well as the total number of observed stars, separately on 2015 and 2023. It should be mentioned that a single star or more can be found in several observation sessions from different stations or in different years.

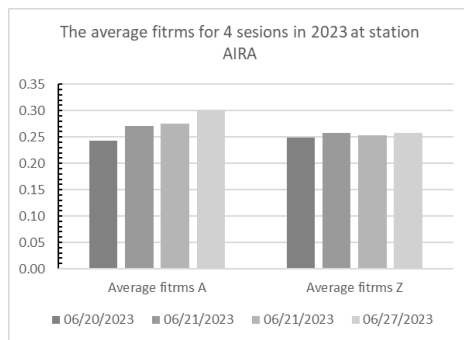


Fig. 8 – Average fitrms in azimuth (A) and zenithal distance (Z), AIRA 2023.

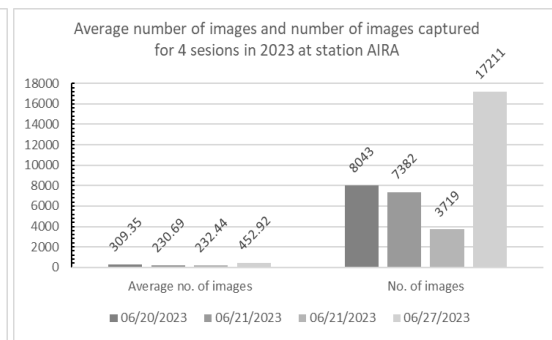


Fig. 9 – Average no. of captured images for every observation night and the total no. of the observed stars.

Figure 10 shows the results obtained, separately for both components of the vertical deviation and all 4 stations (HTL, E, SE, AIRA), from CCD astro-geodetic measurements, and similar values extracted from models (DTM, EGM2008, GOCE) by interpolation.

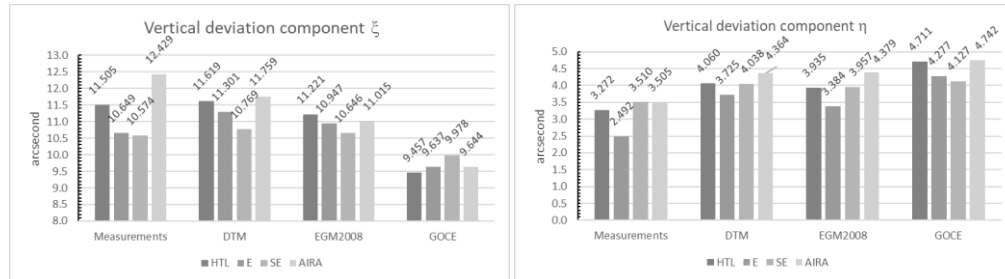


Fig. 10 – Vertical deviation components in all 4 stations from in-situ measurements and models (by interpolation).

Figure 11 shows the individual standard deviation resulted from measurements, for every session of observations, separately by components: $s_{(0)}$ standard deviation of a single series; $s_{(\xi)}$ standard deviation of the meridian component ξ , $s_{(\eta)}$ standard deviation of the prime vertical component η , all values expressed in arcseconds.

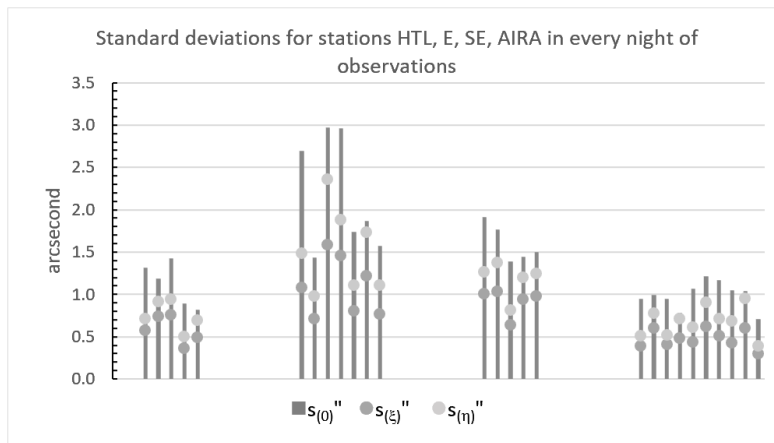


Fig. 11 – Individual standard deviation resulted from functional stochastic model in all 4 stations (also, see the Table 2).

Differences between our results and values extracted from DTM model are under 1 arcsec with a single exception at the station E, for the η component (-1.233 arcsec). The station E was a problematic station, taking into account the largest individual standard deviation obtained, although the measurements were performed in the same way in all stations. It should also be said that the E station is relatively close to the intensively traveled ring road of Bucharest even at night, the road being parallel to an electrified railway line (25 m to the railway and 75 m to the road). However, the values extracted by interpolation from the DTM model are very valuable for comparisons because it is based exclusively on astro-geodetic (historical) determinations.

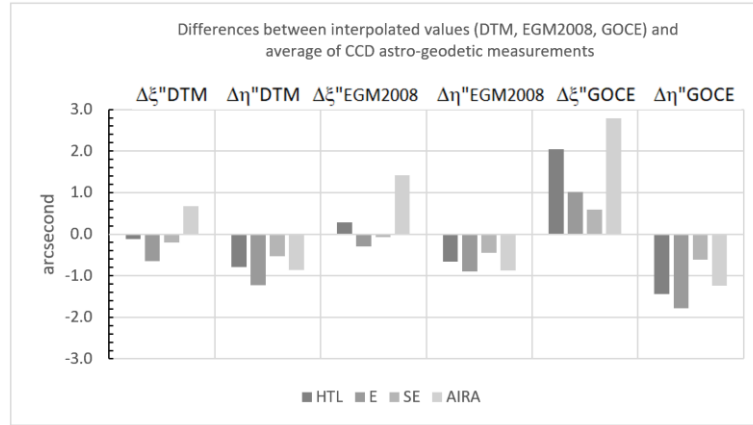


Fig. 12 – Differences between our determinations and used models DTM, EGM2008 and GOCE, separately by components ξ and η .

Differences between our results and values extracted from EGM2008 model also are under 1 arcsec with a single exception at the station AIRA, for the ξ component (+1.414 arcsec). There is an acceptable agreement with EGM2008 global model, approximatively arc-second, in accordance with results obtained in other studies (Featherstone W.E. and Morgan L., 2007; Hirt C., et al., 2010b; Voigt, C. and Denker, H., 2011; Pavlis N.K., et al., 2012).

The worst results were obtained in comparison with vertical deviations derived from GOCE global model. The agreement between CCD astro-geodetic deviations and deviations derived from GOCE exceeds the values obtained in other studies. A study already started (Gornea, A.I., et al, 2017), and future work will be done to clarify the problem.

We consider that the results obtained are promising, especially with the long temporal distance between data of acquisitions (2015, 2023). Future work will focus on achieving a more consistent program of observations/measurements, densifying the number of astro-geodetic stations and making at the same time a consistent statistical evaluation of the results obtained.

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